

# Hysteresis Notation for Near-Zero Representation in High-Precision Contexts

## Overview

In certain high-precision domains (e.g. high-frame-rate video, signal processing, quantum computation, etc.), the representation of zero is problematic due to entropy, noise, and physical impossibility of achieving a perfect null. This proposal introduces a symbolic and notational system to denote a functional "zero range" or hysteresis window surrounding the conceptual zero, with customisable resolution and directionality.

### 1. The Problem with Zero

Zero, as a mathematical concept, is often misused in engineering systems where true null is physically unattainable. Even in digital systems, fluctuations near zero due to noise or quantisation errors mean that some tolerance must be assumed. Without an explicit notation for this margin, ambiguity and misinterpretation may arise.

### 2. Proposed Symbol: Crossed Zero ( $\oslash$ )

A zero with a double slash (like a slashed zero but with both forward and backward diagonal slashes) is proposed to denote a defined hysteresis range around zero. This can be considered a symbolic operator with contextual numeric parameters.

### 3. Greek Letter Encoding: Zeta ( $\zeta$ )

To embed hysteresis-aware tolerances in formulas or metadata, we introduce the Zeta notation:

$\zeta^{60-7}$

This notation denotes a symmetric hysteresis window spanning from  $-10^{-7}$  to  $+10^{-6}$ . In general, the notation takes the form:

$\zeta^{+0-}$

Where:

- Superscript  $^+$  represents the order of magnitude for the positive tolerance
- Superscript  $^0$  (middle) is a placeholder to denote zero as the centre reference
- Superscript  $^-$  represents the order of magnitude for the negative tolerance

Examples:

- $\zeta^{10-2}$  = tolerance from  $-10^{-2}$  to  $+10^{-1}$
- $\zeta^{50-5}$  = symmetric tolerance of  $\pm 10^{-5}$

### 4. Application Contexts

This system is intended for:

- Signal analysis tools
- High-precision timing and frame sequencing
- Software environments requiring resolution-aware comparisons
- Mathematical modelling that must reflect physical uncertainty near null

## 5. Extensions

The  $\zeta$  notation could be extended to:

- Time domain: e.g., delay tolerances in femtosecond timing
- Spatial domain: drift or micro-vibrations in high-resolution optics
- Control systems: deadband/hysteresis tracking

## 6. Implementation Notes

- Software systems should interpret  $\zeta$  as a range comparator rather than a fixed value
- UI/UX guidelines should treat the  $\oslash$  symbol as a toggle-able tolerance-aware zero
- For digital publication, UTF-8 and MathML support for superscripts and Greek characters is required

This notation bridges the gap between theoretical math and real-world systems. By formalising the ambiguity around zero, we offer engineers, physicists, and mathematicians a clearer way to reason about the smallest values that still matter.

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